

CONTRACT REPORT NO. 337

SHAPED CHARGE JET BREAKUP STUDIES USING RADIOGRAPH MEASUREMENT AND SURFACE INSTABILITY CALCULATIONS

Prepared by

Dyna East Corporation Wynnewood, PA 19096 JUN 13

April 1977

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UNCLASSIFIED		(19)
SECURITY CLASSIFICATION OF THIS PAGE (When Date En	(ered)	
REPORT DOCUMENTATION P	AGE	READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER 2.	GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
BRL CONTRACT REPORT NO. 337		ORLECT-SE/1
4. TITLE (and Sublifie)		S. TYPE OF REPORT & PERIOD COVERED
SHAPED CHARGE JET BREAKUP STUDIES U GRAPH MEASUREMENT AND SURFACE INSTA	SING RADIO-	Final / Jak
CALCULATIONS .		DF-TP-76-1
7. AUTHOR(4)		8. CONTRACT OR GRANT NUMBER(+)
P. C. Chou J. C. A. Tanzio J. Carleone J. R. D. Cicarelli	(15	DAAD05-75-C-0753
9. PERFORMING ORGANIZATION NAME AND ADDRESS		10. PROGRAM ELEMENT, PROJECT, TASK
Dyna East Corporation Wynnewood, PA 19096	ŰŢ	61102A 1L161102AJ43
11. CONTROLLING OFFICE NAME AND ADDRESS		17. REPORT DATE
US Army Ballistic Research Laborato Aberdeen Proving Ground, MD 21005	ry (1)	APRES 1977
14 HONITORING AGENCY NAME & ADDRESSIL AUTOMOUT	Controlling Office)	91
IS Army Materiel Development & Dand	incons Commond	IBICI ACCINITED
5001 Eisenhower Avenue	iness command	UNCLASSIFIED
Alexandria, VA 22333		154. DECLASSIFICATION DOWNGRADING SCHEDULE
17. DISTRIBUTION STATEMENT (of the ebetract entered in I	Black 20, il dillerent froz	n Report)
10. SUPPLEMENTARY NOTES This work was supported by the US A Contract No. DAAD05-75-C-0753 and t	rmy Ballistic F	Research Laboratory under
this contract.		
19. KEY WORDS (Continue on reverse side if necessary and is	lentify by block number)	•
Snaped Charge		
Warhead		
Explosive		
Surface Instability		·····
A study of the shaped charge jet bread approaches. In the first approach, jurisdius distributions are measured using from eleven different shaped charge dure related to theoretical predictions and radius curve is presented for copper the concepts of hydrodynamic instabil	<pre>http://www.seck.number/ kup phenomenon et velocity, je ng timed flash esigns. Exper d a semi-empiri lined charges. ity to shaped c</pre>	is undertaken by two et breakup time, and jet radiographs of broken jets rimental results are cor- cal jet breakup time vs. jet The second approach applied harge jets. A
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numerical study of the effects of yield strength, inertia forces, surface disturbance wavelength, and irregular or "Tandom" surface disturbances is presented. Results indicate that high yield strength and low density jet materials will both cause earlier breakup. A critical range of disturbance wave-lengths exists in shaped charge jets; if a random surface disturbance is imposed, a critical wavelength will prevail and eventually cause the jet to breakup into segments with lengths approximately equal to experimentally measured values.

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Acknowledgment

The authors would like to express appreciation to Robert Karpp, Robert Jameson, Julius Simon and John Majerus of BRL for supplying the many jet radiographs used in the present study, and also for the many helpful discussions and suggestions during the course of this work. We would also like to thank Michael Khalil for his help with the many radiograph measurements, computer calculations and data reduction contained here.

I. INTRODUCTION

In recent years, tremendous advances have been made in the basic understanding of shaped charge mechanics. These include the processes of liner collapse, jet formation, and formulas for jet radius and strain. Both two-dimensional computer codes and one-dimensional modeling have been used successfully for the analysis of shaped charges. One important area, however, has not been well understood and cannot be simulated easily by computer methods. This area is the breakup of the shaped charge jet. This breakup, or segmentation, occurs in all jets that have a large velocity gradient with higher speeds at the tip and lower speeds near the tail. This process can be seen in Fig. 1 which shows flash radiographs of a typical shaped charge jet at three successive times, displayed in the proper position-time coordinates. At the earliest time the jet segmentation has begun near the tip; most of the jet is still continuous. The later times show the completely segmented jet.

In [1] and [2], we have presented initial studies on the jet breakup phenomenon. Let us now briefly review the results of these initial studies. Formulas for the strain and radius of shaped charge jets based on a one-dimensional model are presented in [1]. Further, in [1] and [2], a method to determine the jet breakup time distribution from timed flash jet radiographs was developed. This method was then applied to jets from a series of identical BRL 81.3mm standard 42° copper-lined charges and an unconfined 105mm 42° copper lined charge in [1]. Despite the scatter in the results, the breakup time does show a definite "trend" as is indicated in [1]. In fact, for the particular charge studied, the trend indicates that the jet breaks first near the tip with a progressively increasing breakup time towards the tail. Thus, shaped charge jets do not necessarily break simultaneously along their length, as assumed previously by some investigators. The resulting jet breakup time distribution was then contrasted to the one-dimensional theoretical jet strain and radius distributions. This is presented in [1] and [2] where it is concluded that, for copper liners, the breakup time distribution is related to the jet radius distribution. No other correlation was indicated in [1] or [2].

The present study addresses the problem of jet breakup through the use of two approaches: (1) triple-flash radiographs of various jets to determine jet velocity, breakup time, etc., and (2) surface instability as a cause of breakup.

The first approach is actually an extension or continuation of the work we have presented in [1]. The method of [1] to measure breakup time, jet velocity, etc. from timed flash radiographs is applied here to many jets from various shaped charges having different cone angles, different liner wall thicknesses, liners with tapered walls, different liner materials, and light or heavy confinement. This approach has enabled us to obtain many characteristics of jets from a large crosssection of shaped charges. The data from all of these charges are



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conveniently tabulated and graphically displayed in this report. The geometry of the charges studied are given in Appendix A. The measured jet velocity, breakup time and jet radius are plotted graphically in Appendix B. Appendix C contains a tabular list of this data and in addition includes the aspect ratio of the jet segments and difference in velocity between neighboring particles. All of this data has been analyzed to obtain trends in the breakup phenomenon. The breakup trends have been contrasted with the onedimensional strain and radius predictions using the formulas of [1]. Within an individual jet no general correlation has been observed between breakup time and one-dimensional parameters. The results of the breakup time measurements of all copper jets studied, however, do exhibit a definite trend. This trend yields a semi-empirical design curve for breakup time which can be used in conjunction with a one-dimensional shaped charge model to predict breakup time for copper jets. This first approach is presented in Section II.

The second approach involves the study of the instability caused by various disturbances in the jet with the goal of determining whether or not this instability may cause the jet to breakup. We know from classical hydrodynamics that a continuous liquid jet will break into small segments because of surface instability. The breakup of a shaped charge jet resembles this very much, and our study shows that the shaped charge jet is indeed subject to surface instability. In principle, there are three forces which may cause this instability: surface tension, aerodynamic force, and material strength (elastic-plastic force) in the jet. Both analytical studies and two-dimensional finite-difference numerical calculations were made, and the results indicate that material strength is the main cause for shaped charge jet instability and breakup. In addition, the effect of strain-rate, time of disturbance initiation, and inertia were considered. The results of this stability study are discussed in Section III. Finally, general conclusions are stated in Section IV.

We would like to note that the results presented in this report summarize the work conducted during the entire contract period. Some of these results were presented previously in quarterly progress reports.

II. JET RADIOGRAPH DATA

The results which we presented in [1] indicate that the measurement of jet radiographs provides an efficient and useful procedure to obtain breakup data. Also breakup trends are indicated in [1] which warrant further investigation. In this study, we have therefore continued using this approach to study jets from a large number of charges having different geometries and liner materials.

A. General Approach

The detailed development and equations for the computation of breakup time, jet velocity, etc. from the radiograph measurements are given in [1]. Here, we will give only a brief description of this method. Figure 2 shows the position-time plot of two typical neighboring jet segments labeled as K and K+1. Suppose we have radiographs of these two segments at times t_1 and t_2 as indicated in Figure 2. (Note: in the actual case, we have analyzed three timed flash radiographs, as supplied by BRL). We may then compute the velocity of each segment by measuring how far the segments have traveled during the time t_2-t_1 . In the two radiographs the segments are separated by a gap as shown. Under the assumption that the segments remain at constant length and constant velocity after breakup (which is a good approximation after the jet is completely broken as evidenced by the radiographs), it is a simple matter to trace back the front of segment (K+1) and the rear of segment K until they meet, i.e. the gap becomes zero. The time of this meeting tb is the breakup time of segment K from segment (K+1). This procedure may be applied successively to each pair of particles, i.e. K and (K+1), (K+1) and (K+2), etc., until the complete breakup time distribution is obtained. There is a certain degree of approximation to this procedure. Since the particles do not break successively from one end of the jet to the other, we sometimes have the situation where a larger segment breaks from the main jet, continues to stretch, and then finally breaks into smaller, constant velocity, constant length segments. However, the time between the initial break and the succeeding breaks is small, therefore the procedure may still be applied approximately to this breakup situation. The resulting breakup times have been found to be within the accuracy of the experimental procedures.

This method of determining the breakup time was then applied to jet radiographs from many various shaped charges. These radiographs were obtained from BRL through the courtesy of R. Jameson, R. Karpp, J. Simon and J. Majerus. For convenience, the different charges are listed in Table I; the detailed geometry and drawings of each are given in Appendix A. It can be seen from this table that we have studied the effects of cone angle, wall thickness, wall taper, and liner material on the breakup mechanism.



POSITION ALONG THE JET &

FIGURE 2. Position-time plot of two typical jet segments showing the method of determining the breakup time from jet radiograph measurements.

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Table I

List of Charges Examined^{*}

Copper Lined

Charge	Cone	Diameter	Wall Thickness
No.	Angle		
1	20°	38.1	1.168
2	40°	38.1	1.168
3	60°	38.1	1.168
4	90 °	38.1	1.168
5	42°	50.8	0.762
6	42°	50.8	1.524
7	42°	50.8	2.540
8	42° **	81.3	tapered wall

Aluminum Lined

Charge	Cone	Diameter	Wall Thickness
No.	Angle		TUID
9	40°	38.1	1.626
10	60°	38.1	1.626
11	90*	38.1	1.626

* Note that we have also performed a breakup study of jets from the BRL Standard 81.3mm charge and the 105mm unconfined charge in [1].

****** Angle of inside wall

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B. Results of Radiograph Measurements

From the measurements of the jet radiographs, we have determined the jet velocity, jet breakup time, and jet radius distributions for all of the charges listed in Table I. Plots of all of the data obtained are given in Appendix B. Figure B1 shows the jet velocity distribution along the length of the jet at a particular time for the series of 31.8mm copper lined charges having cone angles of 20°, 40°, 60° and 90° (Charge Nos. 1-4). Test results of these charges were first reported in [3], where the average breakup time of the complete jet was given. The time base used in all of the present studies is given as t = 0 when the detonation wave reaches the apex of the cone.* From Fig. B1 we see that, for a given liner material, the tip velocity of the jet decreases as the cone angle increases. It should be noted that, for the 20° copper cone, the resulting jet possessed a bifurcated region at the tip portion. We therefore made our radiograph measurements starting from the first fully coherent particle of the jet, which has a velocity of 8.4mm/usec, much smaller than 9.9mm/usec reported in [3]. We should further note that it has been determined that this bifurcated region is caused by supersonic flow in the jet formation region (See [4] for details). None of the other charges examined under this study possessed this bifurcated region.

The jet velocity distributions for the remaining charges are shown in Figures B2-B6. It is interesting to note that Fig. B6 indicates that the 81.3mm tapered wall charge studied here has a higher jet velocity (8.3 km/sec at the tip) than the 81.3mm standard charge with constant wall thickness studied in [1] (7.9 km/sec at the tip). This somewhat surprising result has a fairly simple explanation. Because of the wall taper (thicker at the cone apex tapering linearly toward the cone base), as we proceed from the apex toward the base the liner elements reach higher collapse velocity than corresponding elements of the charge with a constant wall thickness. This effect provides the tapered wall liner with an overall decrease in the collapse angle (i.e. the angle of the collapsing liner with the charge axis, denoted as β in [1]). From the basic one-dimensional jet formation theory [5] a decrease in collapse angle, in general, produces a higher jet velocity. Finally, from rigs. B1-B6 we also observe that the velocity distribution for each of the charges studied is approximately a straight line.

Plots of the breakup time of the jet particles versus their position in the jet at a particular time for the eleven charges examined are given in Figs. B7-B17. The scatter in the results is to be expected because of the nature of the breakup mechanism. In all cases a definite trend in breakup time exists. To demonstrate this trend, a straight line was passed through the data using the method of least squares. This line is also shown in Figs. B7-B17. All of the jets studied exhibit trends which indicate that the tip portion breaks earlier than the rear portion except for the 38.1mm, 40° copper charge (Charge No.2) and the 81.3mm, 42° copper tapered wall

^{*} Except for the data which is tabulated in Appendix C: The data there is based on the initiation time of the main explosive charge. See Appendix C for details.

charge (Charge No.8). Breakup trends for these two charges show that these jets breakup almost simultaneously. Note that since only part of the jet for each charge appeared in the radiographs, these conclusions are only valid for the portion of the jets measured.

Next, the measured jet radius distributions for the eleven charges studied are given in Figures B18-B28. We see from Figs. B18-B21 that for copper lined charges of a given diameter and wall thickness the average jet radius increases with increasing cone angle. This effect is not so pronounced in the case of the aluminum lined charges as can be seen from Figs. B22-B24. Further, we note from Figs. B25-B27 that, all else being equal, relatively large increases in wall thickness give only small increases in jet radius.

Finally, all of the data resulting from the radiograph measurements are tabulated in Appendix C. In addition to the jet velocity, breakup time, and jet radius, which were graphically displayed in Appendix B, we have also tabulated the aspect ratio (length to diameter, l/d) of each segment and the jet velocity difference between neighboring segments ΔV_{1} . The average ℓ/d and average ΔV_{1} are summarized in Tables II and III. In these tables, we have also summarized this data for the BRL Standard 81.3mm and 105mm unconfined charges which were studied in [1]. Since there was a certain amount of scatter in these quantities, the coefficient of variation (standard deviation divided by the mean) in each case was also computed. From Table II we see that the average l/d varies between 4 and 6 for copper lined conical charges of constant wall thickness. The tapered wall cone has an l/d ratio of 3.3 which may indicate that, even though this charge has a higher tip velocity than the corresponding constant wall charge, its penetration performance at longer standoffs may be poorer because of the small segment size and early breakup time. The aluminum lined charges studied have average ℓ/d ratios of 3.89, 4.92, and 8.39.

From Table III we observe that the overall average velocity difference between neighboring segments for the copper lined charges is approximately 110m/sec. Recently, Held [6] has published that the average ΔV_j for the copper lined German charges he studied was approximately 100m/sec. For the aluminum lined charges studied here, we found an overall average ΔV_j of 145m/sec. Finally, we obtained radiographs of a copper lined French charge, the ISL "S2T", from Perez [7] and found the average ℓ/d to be 5.62 and the average ΔV_j to be 137m/sec. Data of this nature is useful in obtaining rough estimates of the number of jet segments in newly designed charges.

C. Comparison of Data with Theory

In [1] and [8] an improved one-dimensional theoretical shaped charge model was developed. This improved model is based on the classical Pugh-Eichelberger-Rostoker [5] theory but uses a semiempirical collapse formula to describe the explosive-metal interaction process. Further, formulas for jet strain and jet radius were

Table II

Average Aspect Ratio (1/d) of Jet Segments

Cor	ppe	r l	Lir	ied –

Charge No.	Geometry (Dia., Cone Angle, Wall Thk.)	l/d (Average)	Coeff. of Variation
1	38.1 mm, 20°, 1.168 mm	4.69	.520
2	38.1 mm, 40°, 1.168 mm	5.95	.411
3	38.1 mm, 60°, 1.168 mm	5.91	.447
4	38.1 mm. 90°, 1.168 mm	4.49	.301
5	50.8 mm, 42°, 0.762 mm	4.18	.412
6	50.8 mm, 42°, 1.524 mm.	4.48	. 361
7	50.8 mm, 42°, 2.540 mm	4.48	.336
8	81.3 mm, 42°, tapered	3.31	.417
*	81.3 mm. 42°. 1.905 mm	5.93	. 375
*	86.4 mm, 42°, 2.921 mm	5.21	. 324
	Average l/d for all copper jets C.V.	4.86 .180	

Aluminum Lined

Charge No.	Geometry (Dia., Cone Angle, Wall Thk.)	l/d	Coeff. of Variation	
9	38.1 mm, 40°, 1.626 mm	3.89	.454	
10	38.1 mm, 60°, 1.626 mm	4.92	.420	
11	38.1 mm, 90°, 1.626 mm	8.39	. 426	
	Average l/d for all Al jets C.V.	5.73 .411		

* These charges were studied in [1] and this data is included here for completeness

Table III

Average Jet Velocity Difference Between Neighboring Segments (ΔV_4)

Copper Lined

Geometry			
Charge No.	(Dia., Cone Angle, Wall Thk.)	۷۷ <u>۱</u> (m/sec)	Coeff. of Variation
1	38.1 mm. 20°, 1.168 mm	106	.474
2	38.1 mm, 40°, 1.168 mm	111	. 367
3	38.1 mm, 60°, 1.168 mm	135	. 335
4	38.1 mm, 90°, 1.168 mm	109	. 344
5	50.8 mm, 42°, 0.762 mm	110	. 497
6	50.8 mm, 42 [*] , 1.524 mm	115	.522
7	50.8 mm, 42°, 2.540 mm	119	. 449
8	81.3 mm, 42°, tapered	108	.519
*	81.3 mm, 42°, 1.905 mm	96	.557
*	86.4 mm, 42°, 2.921 mm	113	.445
	Average ΔV_i for all copper jets	112	
	J C.V.	.090	

Aluminum Lined

Charge No.	(Dia., Cone Angle, Wall Thk.)	∆V _j (m/sec)	Coeff. of Variation
9	38.1 mma, 40°, 1.626 mm	143	. 362
10	38.1 mm, 60°, 1.626 mm	130	.528
11	38.1 mm, 90°, 1.626 mm	<u>162</u>	.154
	Average ΔV_{4} for all Al jets	145	
	J C.V.	.111	

* These charges were studied in [1] and this data is included here for completeness.

developed for this model. Since the publication of [1] and [8], we have improved this model further by incorporating the effect of liner acceleration during collapse. This enables the prediction of the inverse jet velocity gradient region during formation.

This improved one-dimensional model was applied to the eleven charges studied here. In Figs. B1-B6 the theoretical jet velocity distribution of each charge is shown in contrast to the experimental data. We see that excellent agreement is obtained between theory and experiment. Note that in Fig. B4 and B5 there is some discrepancy between the experimental tip velocity and the tip velocity predicted by the theory for Charge Nos. 6 and 7. This prediction could be improved by using a different value for the acceleration. At present, the acceleration values used in all the cases are given by a simple empirical formula which depends only on liner density and thickness. For these two particular charges the liner thickness to liner diameter ratio is much higher than the other charges studied and therefore thus simple acceleration formula may be inaccurate for these two charges. Theoretical jet radius distributions were also computed from the onedimensional model at the breakup times t_b . The t_b lines in Figs. B7-B17 were used. As shown in Figs. B18-B28, the theoretical radius distributions compare reasonably well with experimental values.

We next compared the breakup time distribution with the theoretical distribution of other jet properties. The goal here was to find some correlation among these distributions which would indicate controlling parameters in the breakup mechanism. We compared trends in the following properties to the breakup trend: jet strain n, jet radius r_j , and jet strain rate \dot{n} . The quantities n and r_j are defined in [1], and \dot{n} is simply the first time derivative of n defined there. We also contrasted these properties to the amount of time elapsed from the formation of an element until it breaks up. This quantity is the absolute breakup time minus the absolute time when the element is first formed, and is denoted t_b-t_f . The quantity t_b is from the experimental least squares line and the quantity t_f is computed from the onedimensional model.

Since the quantities jet strain, jet radius, and jet strain rate before breakup are continuously changing with time, it is appropriate to compare the breakup time of each segment with these quantities at the time when each segment breaks up. To do this, we first trace back each segment in the radiograph to its original position in the cone, x, using the one-dimensional model. We are then able to compute \neg , r_j , and \neg of the segment at its own particular breakup time from the least squares experimental trend. Figure 3 shows a plot of \neg , r_j , \neg , t_b and t_b-t_f versus x/h for the 38.1mm, 60° copper charge (Charge No.3). Note that x denotes the original liner position and h denotes the original height of the cone. Also plotted in Fig. 3 is r_j at t = 55 usec which is a time before any breakup has occurred.





Figure 3 indicates that there is no reasonable correlation between the breakup time distribution and n at t_b or n at t_b . Both the rj at t_b and rj at 55 usec appear to follow the general trend of the breakup time. Plots similar to Figure 3 for the remaining 10 charges were also plotted but are not presented here in the interest of space*. However, the results indicate that within one jet even r_j at t_b and r_j at a time before breakup may not follow the trend of breakup time. Results do indicate that for copper lined charges r_j at a time before breakup seems to increase as the breakup time increases but no general conclusion may be drawn.

We next looked at the breakup data from all the copper lined charges together rather than just throughout a single jet. In Fig. 4 we have made a plot of t_b-t_f vs. r_1 at t_b for all of the copper lined charges studied here (Charge Nos. 1-8). Also, in Fig. 4, we have plotted the data for the 81.3mm BRL Standard Charge and the 105mm unconfined charge studied in [1]. Three data points were selected from each jet. With the exception of one charge, the 38.1mm, 90° copper (Charge No.4), all of the data points for t_b-t_f fall within a narrow region monotonically increasing with increasing r_1 . We may speculate that the 90° charge does not fall in this region because the low collapse velocities in a charge with a large cone angle results in lower pressures and velocities at the stagnation point during formation. Therefore, the properties of this jet may be different from those of smaller angle cones. Figure 4 indicates a correlation between the two quantities for the other charges however. In fact, if we draw a line through these points, we obtain a useful breakup time vs. radius curve, which can be used for design purposes. For example, suppose we design a new copper lined charge and wish to obtain its breakup time distribution. We can compute the radius of the elements of the jet as functions of time. If we then plot the radius vs. time curve of a particular jet element on the breakup time vs. radius coordinates, we find that this curve will intersect the breakup curve. This intersection gives the breakup time of that element. We then repeat this procedure for a series of jet elements. This then yields a breakup time distribution for the new charge. This breakup time information may then be used together with other information on a penetration analysis to evaluate the final performance of the new design.

* These plots for the remaining 10 charges may be found in [9] and [10].





III. STABILITY OF SHAPED CHARGE JETS AS A CAUSE FOR BREAKUP

A. Background

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The concept of liquid jet stability in classical hydrodynamics has been studied by many authors (e.g. [11]-[14]). The idea of applying a stability approach to shaped charge jets was motivated by the remarkable resemblance of the breakup of shaped charge jets to that of liquid jets. This resemblance is shown in Fig. 5 where the breakup of a glycerine-water jet [15] is contrasted with a typical shaped charge jet. Further, we note that the average ℓ/d ratio for all of the copper jet segments studied, 4.86 (see Table II), is very close to the value of the critical $\lambda/2r_0$ ratio of 4.5 predicted by classical stability analyses of liquid jets, where λ is the wavelength of the surface disturbance, and r_0 is the radius of the undisturbed jet. These facts suggest that the shaped charge breakup phenomenon may be caused by surface instability.

The first stability analysis of a liquid jet was published in 1879 by Lord Rayleigh [11]. He considered an inviscid fluid jet moving at a constant uniform axial velocity subjected to surface disturbances about the equilibrium position. He obtained the most unstable wavelength and the perturbation growth rate using energy considerations. His values of wavelength and growth rate have been verified by experiments, and his work is still considered the foundation for the study of jet stability.

Weber [12] extended Rayleigh's work to include viscous Newtonian fluids. The wavelength of the most unstable surface disturbance for a viscous fluid does not deviate too much from the ideal fluid case of $(\lambda/2r_0) = 4.5$. He also found that Newtonian viscosity tends to dampen the instability. Anno [16,17] gave a more general derivation of the analyses by Rayleigh and Weber.

Goldin, et al [15] studied the breakup of non-Newtonian viscous fluid jets. They used essentially the same approach as Levich [13] and obtained results on critical wavelength, growth rate, and breakup time for fluids possessing general viscoelastic stress-strain relations. In [15], it is shown that the Newtonian fluid is the most stable one among viscous fluids. Experimental evidence for different types of fluids seems to verify their results.

In our initial work, we have determined that three effects may cause jet breakup: surface tension, aerodynamic forces, and strength of the jet material. We have applied all the essential results of the classical analyses to the conditions of a typical shaped charge jet. We have also examined many experimental breakup records in the light of stability considerations. These results have ruled out the importance of the surface tension and aerodynamic effects in the stability of a shaped charge jet. This leaves the effect of jet strength. Since strength effects are not readily amenable to analytical treatment, we have turned to numerical approaches to study the

LIQUID JET 75 % GLYCERINE-25 % WATER REFERENCE 15

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SHAPED CHARGE JET COPPER 81.3MM BRL STANDARD (RADIOGRAPH COURTESY R. JAMESON, BRL)

FIGURE 5. The resemblance between the breakup of a liquid jet and a shaped charge jet.

effects of jet strength.

In the next section of this report, we will first present results of a preliminary analytical study. Then more detailed results on the numerical study will be presented, including the study of various surface disturbances, time of disturbance initiation, strain rate, and inertia effects in jets with strength.

8. Preliminary Analytical Stability Study of Shaped Charge Jets

The results and formulas developed in the classical analyses of liquid jet stability were applied to the case of a typical shaped charge copper jet. Analyses for non-stretching and stretching jets were used. The results of this study are summarized in Table IV and will be briefly discussed below.

1. <u>Non-stretching Jets</u>

(a) <u>Surface Tension</u>. In our initial analysis, we have applied the classical formulas of Rayleigh [11] and Weber [12] to the conditions of a typical copper shaped charge jet. Rayleigh's work governs the case of an ideal fluid under the effect of surface tension and Weber's results are applicable to a viscous fluid under the effect of surface tension. The growth rate of disturbances on the surface of the jet as predicted from these formulas is quite small as compared to that observed in radiographs of shaped charge jets. In fact, according to these formulas the amplitude of the initial disturbance only grows 8% in 100 usec, whereas it is observed from experiments that the shaped charge jet used for this analysis breaks up at approximately 100 usec. The value of surface tension for copper used was 1.0 N/m.

(b) <u>Aerodynamic Force</u>. We have applied the formulas of Levich [13] to the problem of air passing over a shaped charge jet. A verv large disturbance growth rate was predicted by this analysis. We feel, however, that the analysis is not too realistic for the present problem since Levich only considers linear incompressible aerodynamics and the present case is actually in the hypersonic regime. We would also like to indicate two experimental observations which demonstrate that aerodynamic effects are not important in the breakup of shaped charge jets. Vitali [18] has pointed out that superplastic jets do not breakup along their length in the typical manner of a copper jet, yet both jets are subject to the same aerodynamic force. Also, Frey [19] has studied photographs of copper jets in a vacuum, and found the typical surface disturbance growing within 100 usec, similar to those found in jets traveling through air.

2. Stretching Jats

Mikami, et al [14] has developed an analytical approach to study the growth of disturbances on the surface of a stretching viscous thread surrounded by another viscous medium. We have modified this analysis to make it applicable to the case of a shaped charge jet. As shown in Table IV, appreciable growth rates and reasonable $\lambda/2r$ ratios

Table IV

Analytical Approaches to Shaped Charge Jet Stability

Other Comments		used incompressible aerodynamics, not realistic for present case.	inertia force neglected in governing equations	:
Disturbance Growth Rage	87 in 100 µsec	1000 X in 22 µsec	100% in 64 usec	100 1 in 16 µsec
Most Unstable \/2r	4.5	4	8.9 after 64 µsec (broad range)	5.2 after 16 µsec (broad range)
Surface Forces	Surface tension	Aerodynamic force	None	Surface tension
Medium	both ideal and viscous fluids	viscous (Newtonian)	viscous (Newtonian)	viscous (Newtonian)
Stretch- ing	ou	ou	yes	yes
Approach	Rayleigh	Levich	Present s tudy	Present study

were predicted by this analysis at times in the regime of typical breakup times: (Note that in the stretching jet case $\lambda/2r$ changes with time thus making the comparison more complicated.) However, the approach of [14] has neglected inertia forces to make the governing equations analytically tractable. Because of the high strain rates present in the shaped charge problem inertia effects will be important. This importance of inertia effects will be verified by numerical calculations in the next sub-section. Thus, we feel that the results of this analytical method of [14] as applied to the shaped charge problem are not conclusive.

C. Numerical Study of Shaped Charge Jet Stability

In the previous sub-section we have studied surface tension and aerodynamic effects on jet stability by relatively simple analytical techniques. Since effects such as material strength are, at present, not readily amenable to analytical treatment, we have used numerical techniques to study this and other effects. One advantage of numerical studies over analytical studies is that in the numerical treatment all of the pertinent effects may be included at the outset, whereas analytical treatments necessitate the use of certain simplifying assumptions.

1. General Approach

The numerical study of jet stability was undertaken through the use of the two-dimensional code HEMP [20,21]. The HEMP code is a general purpose code which solves the conservation equations of twodimensional elastic-plastic flow in plane coordinates or in axisymmetric coordinates. The solution is by the method of finite differences and uses the Lagrangian formulation. The code has the capability of handling many various boundary and initial conditions.

Karpp [22] first applied HEMP code calculations to the problem of a stretching elastic-plastic jet with the surface slightly disturbed. After calculating various wavelengths of the surface disturbance, he found a broad range of most unstable wavelengths with reasonable growth rates. We have applied the same basic method to study the breakup problem in more detail. The boundary and initial conditions of this method will now be briefly described.

A stretching shaped charge jet is modelled by a prismatic circular bar fixed at one end, with the other end moving at a constant velocity. A linear velocity distribution in the axial direction is imposed as the initial condition, and the surface of the bar is initially perturbed in the shape of a cosine function, as shown in Fig. 6. The perturbed surfaces are free from any tractions and the end surfaces are free of any shear stresses. Let the axial velocity be V(x,r,t), the radial velocity be u(x,r,t), the stress vector on the lateral surface be $g(x,r_s,t)$, and the shear stresses on the end surfaces be $\tau_{rx}(0,r,t)$, $\tau_{x\theta}(0,r,t)$, $\tau_{rx}(L,r,t)$, $\tau_{x\theta}(L,r,t)$, then the boundary conditions are



FIGURE 6. Initial and boundary conditions for the numerical jet stability computations.

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$$V(0,r,t) = 0V(L,r,t) = V_0(1)
$$\frac{d}{\tau_{rx}(0,r,t)} = \tau_{x\theta}(0,r,t) = \tau_{rx}(L,r,t) = \tau_{x\theta}(L,r,t) = 0$$$$

and the initial conditions are

$$V(x,r,0) = (V_0/L)x$$
 (2)
 $u(x,r,0) = 0$

The calculation may often be limited to only one cycle of the surface wave along the axial direction because of the symmetry of the problem.*

2. The Effect of Yield Strength

In the analytical studies discussed previously all of the jets were assumed to be fluid in nature and the driving forces for the instability were restricted to surface tensions, viscosity, and aerodynamic forces. Now we will study the effect of yield strength on the stability of an elastic-plastic jet.

To study this, we computed four jet segments having different yield strengths but being otherwise identical. In these calculations we selected a copper jet segment with one cycle surface disturbance having an initial length of 7.5mm and an initial mean radius of 1.5mm. The initial amplitude of the wave was taken as 10% of the initial radius. The velocity difference between the two ends of the segment was 0.0625 mm/usec. In a real jet this initial time corresponds typically to a time 50 usec after the segment was formed or approximately 100 usec after the detonation of a BRL 81.3mm charge. This initial configuration and calculation mesh is shown in Fig. 7. In all cases the copper equation of state as specified in HEMP was used. The value of density used was 8.9×10^3 kg/m³ (8.9 g/cm³) and the elastic shear modulus was taken as 4.56×10^{10} Pa (456 kbar). The first of the four segments has no strength, i.e. purely fluid; the next three have yield strengths of 2×10^7 Pa (.2 kbar), 2×10^8 Pa (2 kbar), and 2×10^9 Pa (20 kbar). The configuration after 32 usec for each of these four cases is also shown in Fig. 7. To compare results we have computed a quantity $\dot{\Delta}$, the relative growth of amplitude, which is defined as the difference between the amplitude of the disturbance after stretching, A, and the initial amplitude, A_0 , divided by the initial amplitude, i.e. $(A-A_0)/A_0$. This quantity is also given for each case in Fig. 7. We observe from these calculations that the disturbance grows faster for jets with larger values of yield strength.

- * We are studying a typical element in the middle of the jet. This element is being stretched by the force of the forward part of the jet on one side and the rear part of the jet on the other. The details of how the momentum and energy is transferred from one portion of the jet to another are currently being studied.
- ** Note that Karpp and Simon [23] have recently studied the strength in shaped charge jets using the experimental results of rotating charges and also by using two-dimensional numerical calculations.



INITIAL LENGTH: 7.5MM INITIAL MEAN RADIUS: 1.5MM VELOCITY AT MOVING END: 0.0625MM/ μ sec Δ = relative growth of disturbance = $(A-A_0)/A_0$ y = yield stress (elastic-perfect plastic)

FIGURE 7. Comparison of stretching jets with various yield strengths.

For static applications, we are used to the concept that, when comparing two materials, the one with higher strength will sustain larger stress, larger strain, and more stretching. Our present results indicate, however, that under dynamic conditions, the opposite case, which seems contrary to common sense, prevails. That is, under dynamic conditions of stretching, the material with higher yield stress is more unstable, will neck more, and break sooner.

3. The Effect of Disturbance Initiation Time

In this sub-section the effects of initiating the disturbance at various times in a realistic shaped charge jet are presented. Consider an element of a jet at several stages from the time when it is first formed until the time of its breakup as shown schematically in Fig. 8. This element of jet has an initial velocity difference of 0.13 mm/µsec between its two ends. The initial length and velocity gradient were selected such that, at the breakup time, the element will have a length equivalent to the average measured length of a typical jet segment from a 81.3mm BRL standard charge. We may therefore consider only one wavelength disturbance over this selected element. When this jet element is first formed one-dimensional calculations indicate its length whould be approximately 1.1mm and its radius should be approximately 3mm. The times chosen to introduce the disturbance, labelled t1 through t5 in Fig. 8, correspond to times 0 µsec, 7.92 usec, 17.62 usec, 25.69 usec, and 45.71 usec after the element was first formed, respectively. The overall dimensions of this element at these different times are summarized in Table V.

Table V

Run No.	Time after formation (µsec)	Element Length (mm)	Element radius (mm)	λ/2r	Amplitude of Imposed Disturbance (mm)	Strain Rate (µsec ⁻¹)
1	0	1.10	2.98	0.18	0.149	0.118
2	7,92	2.13	2.13	0.5	0.107	0.061
3	17.62	3.39	1.69	1.0	0.085	0.038
4	25.69	4.44	1.48	1.5	0,074	0.029
5	45.77	7.05	1.17	3.0	0.059	0.018

Dimensions of Jet Element Studied at Various Times After Its Formation



POSITION IN THE JET &

FIGURE 8. Schematic showing a position-time plot of a jet element which stretches to the typical breakup length. Disturbances are initiated seperately at each of the times indicated for independent HEMP calculations of the element.

The HEMP calculations were performed using each of these times as a <u>separate</u> starting point. The disturbance was introduced independently at each of these times and each was treated as a separate problem. The equation of state and other constants for copper stated in the previous problem were again used. The yield stress was 2×10^9 Pa (2 kbar). The amplitude of the imposed disturbance was taken at 5% of the radius in each instance and is also given in Table V.

The five HEMP calculations indicate that, during short times after the initiation of the disturbance, the amplitude of the surface disturbance in Run No.4 grows the largest amount. This can be seen in Fig. 9, where the relative growth, Δ , at a time 18 usec after the disturbance initiation for each case is plotted versus the initial strain rate. This gives an indication of how soon each disturbance begins to grow. As time proceeds, however, and we continue the calculations, the earlier configurations (Run Nos. 1-3) eventually reach a configuration similar to Run No.4, and then the disturbance begins to grow quickly. This can be seen in Fig. 10 where the relative growth of Run Nos. 2,3, and 4 are plotted versus time. Examining Run No.2, we see that the disturbance is stable until a time of approximately 30-35 usec after formation, then the growth rate drastically increases. Run Nos. 3 and 4, in which the disturbance is initiated at times later than Run No.2, also begin to grow more rapidly in the region 30-35 usec. Thus we see that, no matter how early we initiate the disturbance, when a critical time is reached, the disturbance will begin to grow and eventually the same final breakup configuration will be obtained.

4. The Effect of Disturbance Wavelength

The effect of disturbance wavelength was studied by considering a jet of realistic radius and strain rate at a reasonably early time after formation and introducing surface disturbances of different wavelengths. A jet element having an initial radius of 2.13mm and an initial strain rate of 0.061 usec^{-1} was used. The equation of state and material constants for copper stated in the previous problem were again used. Four separate surface discurbances having initial wavelengths of 1.065mm, 2.13mm, 4.26mm, and 8.52mm were introduced and HEMP calculations made for each case. Note that we have chosen this problem such that the case $\lambda = 2.13$ mm will eventually grow to the observed segment length after the experimentally determined breakup time for a typical shaped charge jet. Let us denote this "correct" initial wavelength as $\lambda_0 = 2.13$ mm. We can then denote the other cases as $\lambda = \lambda_0/2$, $\lambda = 2\lambda_0$ and $\lambda = 4\lambda_0$. The relative growth, as computed using the HEMP code for each of these cases, is plotted vs. time in Fig. 11. From this plot we see that the disturbances having initial wavelengths of $\lambda = \lambda_0/2$ and $\lambda = 4\lambda_0$ grow very slowly. The wavelength $\lambda = \lambda_0$, which will grow into the proper segment size, grows very quickly but not quite as fast as the case $\lambda = 2\lambda_0$.


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FIGURE 11. Relative growth vs. time for surface disturbances of four different wavelengths. In all cases, the jets initially have the same radius and strain rate.

5. Irregular Surface Disturbance

To examine these wavelength effects further, we have numerically studied jets having an irregular surface disturbance. In previous cases, we have considered jets having a surface of a single sinusoidal curve. Next, we have combined the four wavelengths of the previous study to obtain an irregular surface disturbance which is described by the following function:

$$\mathbf{r_s} = \mathbf{r_0} + \mathbf{A_0} \underbrace{\sum_{i=1}^{4} \cos \frac{2\pi \mathbf{x}}{k_i}}_{i=1}$$

where $k_1 = \lambda_0/2$, $k_2 = \lambda_0$, $k_3 = 2\lambda_0$, $k_4 = 4\lambda_0$. We have taken numerical values to be $r_0 = 2.13$ mm, $\lambda_0 = 2.13$ mm, $A_0 = 0.026$ mm, and the initial strain rate equal to 0.061 μ sec⁻¹. We again used the material constants for copper described previously. The initial configuration which has a length of $2\lambda_0$ is shown in Fig. 12, together with the configuration after 52 usec. We observe that the jet appears to neck in two places. This indicates that λ_0 is the dominant or fastest growing wavelength, which is in agreement with the experimentally obtained segment length. To demonstrate this more quantitatively, we have fit a Fourier series to the outer surface of the configuration after 52 usec shown in Fig. 12 and have examined the coefficients of the terms of each wavelength. Denoting the length after 52 μ sec as $2\lambda_1$, we observe that the largest of all the Fourier coefficients is that of the term containing the length $\cdot = \cdot_1$. A comparison of the coefficients of the four wavelengths of interest are also shown in Fig. 12. Thus, this result indicates that the component with an initial wavelength of $\lambda = \lambda_0$, which stretches into $\lambda = \lambda_1$ after 52 usec is the most critical one.

In the case above, the initial disturbance consists of four waves of different wavelength, which are all "in phase". We performed yet another irregular surface disturbance calculation. In this calculation, a "random" disturbance was used which was comprised of five waves of different wavelength and phase angles, so that the waves would not be "in phase" at the ends. Thus, this new disturbance represents more closely a random one. The function used for the surface was

$$\mathbf{r}_{ij} = \mathbf{r}_{ij} + \mathbf{A}_{j} \frac{\mathbf{b}}{\mathbf{i} = 1} \cos \left(\frac{2\pi \mathbf{x}}{\mathbf{k}_{i}} - \mathbf{i}_{i} \right)$$

where $k_1 = k_0/2$, $k_2 = k_0/4$, $k_3 = k_0$, $k_4 = 3k_0/2$, $k_5 = 2k_0$, and $k_1 = 27^\circ$, $k_2 = 36^\circ$, $k_3 = 48^\circ$, $k_4 = 54^\circ$, $k_5 = 3^\circ$. Numerical values were taken as $k_0 = 2.13$, $k_1 = 2.13$ mm, $k_0 = 0.053$ mm, and the initial strain rate equal to 0.061 usec⁻¹. The initial configuration and the configuration after 48 usec of stretching as calculated by the HEMP code are shown in Fig. 13. We see the jet necking in two places which again indicates that the growth of the $k_1 = 100$ wave predominates and that the proper set segment length will be attained at breakup.

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b. CONFIGURATION AFTER 48 #Sec

FIGURE 13. Results of HEMP calculations of a stretching jet with "random" surface disturbances.

6. The Effect of Inertia

To study the importance of inertia effects on the growth of surface disturbances in stretching shaped charge jets, we have made HEMP code calculations of three jets. Each jet was identical in all respects except for the density of the material used in the calculations. The configuration used was the standard single wave surface disturbance depicted in Fig. 6 with $r_0 = 2.13$ mm and wavelength equal to 2.13mm. The initial amplitude used was $A_0 = 0.107$ mm and the initial strain rate equal to .061 µsec⁻¹. The equation of state and material constants described previously for copper were used except now three different values of density were used $\rho_0 = 1x10^3$ kg/m³, $\rho_0 = 8.9x10^3$ kg/m³, and $\rho_0 = 16.5x10^3$ kg/m³. The relative growth vs. time for each case is plotted in Fig. 14. We observe that increased density, i.e. increased inertia force, has a retarding effect on disturbance growth.



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FIGURE 14. Relative growth vs. time for the stretching jets of different densities as predicted by HEMP.

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IV. CONCLUSIONS

The major results and conclusions of the present research may be summarized as follows:

A. Measurement of Jet Radiographs

1. Data from jet radiographs, including jet velocity, breakup time, and segment size, for jets from eleven charges were compiled and plotted for easy reference.

2. These measured jet velocity and jet radius data agree closely with those calculated from a one-dimensional shaped charge model.

3. Analysis of this data together with using onedimensional calculations resulted in a semi-empirical breakup time vs. jet radius curve for copper jets. This curve can be used to estimate an approximate breakup time for new charge designs.

B. <u>Stability of Shaped Charge Jets</u>

1. Simple stability analyses and experimental results indicate that surface tension and aerodynamic forces are not important in the breakup of shaped charge jets.

2. Numerical HEMP code calculations of stretching elastic-plastic jets subjected to surface disturbances were conducted. The effects of material yield strength, time of disturbance initiation, wavelength of the disturbance, irregular surface disturbances and jet density were examined. The following results were found:

a. Jets with higher yield strengths break sooner, all else being equal.

b. Jets with lower densities will break sooner, all else being equal.

c. For the shaped charge jet calculated, there is a critical time for the growth of the disturbance amplitude. Disturbances introduced early do not grow appreciably before this time, but grow rapidly after this critical time. Disturbances introduced after this time also grow rapidly.

d. A critical wavelength (or a range of wavelengths) exists; disturbances having this wavelength grow faster than all others. The length of the broken jet segment caused by this critical wave is in the range of measured jet segment lengths.

e. When irregular, or random, surface disturbances are introduced, the growth is again dominated by the disturbance component with the critical wavelength. The jet surface grows into a shape similar to that obtained if only the wave with the critical length were introduced.

3. Materials with high density and low yield strength are promising liner materials which will likely retard the breakup of the resulting jet.

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Appendix A

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This appendix contains the specifications of the eleven charges studied in this report.

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FIGURE A1. Geometry of the 38.1 mm Copper and Aluminum lined charges with various cone angles. (Charge Nos. 1-4,9-11) (from Ref. 3)

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FIGURE A2. Geometry of the 50.8 mm, 42° Copper lined charges with different wall thicknesses. (Charge Nos. 5-7) (Courtesy of R. Jameson)

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FIGURE A4. Details of the 81.3 mm, 42^o tapered liner. (Charge No. 8) (Liner was made at BRL.) (Courtesy of R. Jameson)

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Appendix B

This appendix contains a graphical display of jet velocity, jet breakup time, and jet radius data computed from the jet radiographs of the eleven charges studied in this report.

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FIGURE B1. Theoretical and experimental jet velocity vs. jet particle position for the series of 38.1mm, 1.168mm wall, copper lined charges with various cone angles at various times after the arrival of the detonatic wave at the cone apex. (charge nos. 1-4).

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FIGURE B2. Theoretical and experimental jet velocity vs. jet particle position for the series of 38.1mm, 1.626mm wall, aluminum lined charges with various cone angles, at various times after the arrival of the detonation wave at the cone apex. (Charge Nos. 9-11)

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FluURE B4. Theoretical and experimental jet velocity vs. jet particle position for the 50.8mm, 42°, 1.524mm wall, copper lined charge at 130.5 usec after detonation wave arrival at cone apex. (Charge No. 6)



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FIGURE 85. Theoretical and experimental jet velocity vs. jet particle position for the 50.8mm, 42°, 2.54mm wall, copper lined charge at 130.7 usec after detonation wave arrival at cone apex. (charge No. 7)

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FIGURE B7. Jet breakup time vs. jet particle position at t=107.7 μ sec for the 38.1 mm, 20°, 1.168 mm wall, copper lined charge (charge no. 1).





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(Charge No. 3)





FIGURE B11. Jet breakup time vs. jet particle position at t=113.1 µsec for the 38.1mm, 40°, 1.626mm wall aluminum lined charge. (Charge No.9)



(Charge No. 10)



1.626 mm wall aluminum lined charge. (charge No. 11)





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FIGURE B16. Jet breakup time vs. jet position at t=130.7 usec for the 50.8 mm, 42°, 2.54 mm wall, copper lined charge (charge no. 7).





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FIGURE B26. Theoretical and experimental jet radius vs. jet particle position at t=130.5 µsec for the 50.8 mm, 42°, 1.524 mm wall copper lined charge (charge no. 6).

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FIGURE B27. Theoretical and experimental jet radius vs. jet particle position at t=130.7 μ sec for the 50.8 mm, 42°, 2.54 mm wall copper lined charge (charge no. 7).



FIGURE B28. Theoretical and experimental jet radius vs. jet particle position at t=130.5 µsec for the 81.3 mm 42°, tapered wall copper lined charge (charge no. 8). (Note: The lead particle at 1003 mm in the jet has a radius of 4.6 mm and is not plotted here for convenience.)

Appendix C

This appendix contains tabulated data for the jet velocity, breakup time, length, diameter, radius, aspect ratio and ΔV_j of the jet segments as computed from radiograph measurements for the eleven charges studied in this report.

The breakup times in these tables are referred to t=0 when the charge is first initiated. Throughout the rest of the report, including the plots of appendix B, all times are referred to t=0 when the detonation wave first reaches the apex of the liner cone. The time it takes for the wave to travel from the point of initiation to the apex of the cone for charges 5,6 and 7 is 6.4μ sec; for all other charges this time is 7.0 μ sec.

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"周期前来与他们们有了这些教师之中的一位在了你了。"

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لمتقفقة عاد ف كادة فقد من الاستراف المكفة هم عقدات اللاموات العدام غارا بغابات عمل أمر غيافتين أساس تعملن طفياتيسمينمد

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ALL VALUES ARE THE AVENAGE FROM THREE ARCIUGNAPHS

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•	0 345414+0	U 6.52375E 01	1.0465UL 01	1.520COE UO	4 . 1000UL - 01	5.750006 00	2.04446F -01
n	0 340218.0	U 2.52034E UL	5.30834£ 00	1.97167L UG	V.85833E-01	2.71667F 00	7+194095-02
0	0 361196.0	10 344828. 01	J.741076 00	1.52000£ 00	4.10000L 01	2.083336 00	1. 124315-01
~	0.210725 0	u 5.10243E ul	J. 4 5 5 3 1 5 0 0	1.52000E UN	7.10000L 01	1.41667E 00	1.514275-01
Ð	0.3424CU.0	U 3+425/3E Ul	3.85555 DU	2.123336 00	1.06167E 00	1-000075 00	10-346012+1
>	[. 4302UL U	U 5+10729E 01	d.34167£ 00	1.52000E 00	4.10000E-01	4.58333E Da	2.196145-01
2	1.1105 L	U 2+45928E U	J. 743336 00	1.66833E UU	7. Ja1672-01	2.34869E 00	7.44446E=U7
[]	0 341469. J	U 4.76262E U]	4.0454JE 00	1+02000E 00	4.10000t %	2+25000E 00	1.50973F -01
12	0 301000 J	u 6.18767E UI	4.550UUL 00	1.97167E 00	4.8583JE 01	2+333536 00	1.666195-01
11	10 JEEF16.	U 5.70514E 01	9.555UUL 00	1.82000E UD	4 • 1 000 UL " 01	5.25000E 00	2-043725-01
•	COLUMITE UN	U 5.54147E 01	6.410012 00	1.52000E 00	4.10000E-01	3.633335 00	4.72161E-U2
4	1-U24466 J	U 7.05553E U1		1.51667L 00	7.583336-01	3.13559E 00	2+233165-2
0		U 7.20615E 01	10 JUUC0E.1	1.82000£ 00	4.1000JL-01	7.500006 00	7->7200E-02
1	0.744426 41	U 5.93174E 01	1.3300/L 0C	1.82000L 00	4 • 10000E • 01	1.643331 00	2.044945-01
0	10 324422-0	U 1.30004E 01	1.5800/L 00	1+520005 00	4 - 1 0000F - 0 F	00 361666.4	10-36706-1
5	0.326105.0	U 0.06357E 00	00 3456 00	1.J0500L 00	6+6250UL 01	4.8489E 00	6.43198E - U2
20	**2770JL 01	U 7.33742E DI	4.3703JL 00	1.82000E UD	4 10000L 01	2.416676 00	1.589355-01
7	o-levute OI	10 352401+a A	1.5J71/L 01	1.30500E 00	6.6250UE 01	d.111116 00	[.>9086E"Ul
22	Several L	U 0.45046E 01	4.10000L 00	1. 16500E 00	6.62500L-01	6.66667L 00	138045-01
53	2-43/20F 01	U 7.65544E 01	5.GU5CUE 00	1.420006 00	10- 30000 I · A	2.750006 00	8.70048E-02
24	2.154146 01	9 ••212256 01	00 7/10/F 00	1.42000t 00	<	00 3(FC#5+C	1.094075-01
ŝ	2-64U 14L UL	U 10732706 UI	6.3 ⁷ UUUE OU	1.82000L UU	10, 30000 [· F	3.500001 00	1.455405-01
•	10 368464+6	2 成其其其其其其其其其其	8447335 00	1.52000L 00	4.1000UE-01	4.66667E 00	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
VERA		5.82049E Q1	++8010/E 00	1.8u250£ 00	V.012505 01	3.890386 40	1.430925-01
				STAND	ARU DEVEATION	1.745405 00	5.172965-02
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-	1.4454.1	30	10 382E08.2	10 1/100/1	1.820001 00	v.10004-v	00 3665 8 4.8		
~	1.040.1	3	8-20340E UL	1.0001E 00	1.420001 00				
~	164 : 451	75	1.2311155 01	1.4230/6 01					
•	361604.1	22	4.445/46 01	1.4884/L 00		4 - 100001 - 4			
•	102+02-1	22	10 31/5/1.8	6.6/JJJL 00				10-12500002	
•	1.1/3206	30	6.626V6F 01	7.24004 00					
~	316+14-4	20	1.267375 01	7-12411 00					
10	10/0/0.0	20	0.20+00F UI	2.123336 00	1.520001 00				
,	151201.0	33	0]04246 01	10 366160.1	1.000110 00	0.14147			
n	120504.0	3	D. BECAVAR UL	V. 2310/6 00	1.620005 00	100001-1	South that the		
11	344655.0	20	1. 306401.	0.0444/L 00	1.0.000 DO	10- 400001 • *			
12	360226095	3	10 355 0VA-C	1.591116 00	1.62001 43	4.1000ut - 01			
-	9.14136	20	0 3(2504.0	10 3000/201	1 . B20001 00	10,100001.4	7.000006 00	1.440445	
•	9.00014	20	1.300+01 UI	J. J Joo/L 00	1.5,0001 00	10- 1000C + +	1.441126 00		
4	3040444	22	10 30/010.01	00 3/0174.0	1.520.06 00	**1000L 01	1.561116 00	1.212195-01	
*	308/20.0	20	7.435336 01	1.30200 01	1.84000 00	4.10000 -01	7.54000F DJ		
2	310100.0	2	0.51533E UL	5.308JJE 00	1.52006 00		2-914675 00	5-80441-02	
	10616606	20	10 305015.0	1.4316/L 00	1.42000£ 00	4 . 1 JOOUL "01	00 3116 00.0		
>	3+40045-6	20	10 342/20.2	5.40JUVE 00	1.02000 00	4.10000L-U1	1.000001 0.1	4-247145 -02	
20	312/26.0	20	4.67324E Ul	5.44UULE 00	1.820001 00	4 • 10004 - 01	1.00000 00	1.000155-01	
1	344402.0	3	1-07471 02	1.5166/L CI	1.52001 00	4.1000L -01	0. 311111 00	20-301010-6	
2	34/261.0	3	10 300414·A	1.076036 01	1.42000E 00	4.10000L-V	5.91447E 00	10-398695-2	
2	3000.0.4	2	1.043166 U2	1.2/4006 01	1.820096 00	4.1000L-01	7.900006 00	1.374805-01	
	176661	2.	V.15424E 01	Y.535446 00	1.42000L 00	V.1000UL-01	3.250006 00	20-367166-1	
ŝ	300+21++	2	1.003055 02	1.042016 01	1.82000L UU	10-300001.*	80 300777.4	20-30000.5	
•	4.46/316	20		+.3/UUUE 00	1.82000L UD	v.100006-01	3.50006 80	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
	•		7.94058E UI	6.62UUUE 00	1.746672 40	0.98333£ 01	4.414476 80	1-795542-1	
					STAND	ARU DEVEATION	2.003435 00	20-3006(8-9	
					CUEFF.	OF VANLATION	10-322461-0	10-310002-6	

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ALL VALUES ANE INE AVENAGE FURN THMEE MAUJUGMAPHS

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•	60 20 1 8 4 4	1. 300000	10 306469.1	1.520001 40	1. 10000	1.175006 01	10-3146/0-1
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• •			I TENZE	1.420004 00	4.100UUL -01	A.175006 01	10-3/2510-1
• •			1.117546 01	1.92001 0.1	••1.000t ••1	00 100057.1	10-3146 /0-1
, ,			I fault 01	1.420001 00		7.uuuunt 00	10-10+6×2+1
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.			10 34/2451	1.92000 40	<pre>/•100001-></pre>	00 JOUR200	15-326044-3
. 1				1.8,000 00	10 10001 ··	4.0000 BO	コラー ゴクラ サクフォイ
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			I.A Shull OI	2.110.001 0.0	1.165046 00	8. UUUUU UO	10-3512/1-1
				2.477.04 40	1.477754 00	4.416671 UD	10-34217501
23			1.4/4/21		1. 148736 00	••150001 00	
AVENU	1.1	1.124765 02	1.72/3/6 01	2.210001 03	1.105006 40	9. Jerev. UD	1.010315-01
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